Título da Dissertação-Tese
Subtítulo se aplicável

Por

Nome Completo do Aluno

Orientador: Nome do Orientador 1

Co-orientador: Nome do Orientador 2

Tese submetida à
UNIVERSIDADE DE TRÁS-OS-MONTES E ALTO DOURO
para obtenção do grau de
DOUTOR
em Engenharia Electrotécnica e de Computadores, de acordo com o disposto no
DR – I série–A, Decreto-Lei n.º 74/2006 de 24 de Março e no
Regulamento de Estudos Pós-Graduados da UTAD
DR, 2.ª série – Deliberação n.º 2391/2007

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Orientação Científica :

Nome do Orientador 1

Professor Associado com Agregação do
Departamento de Engenharias
Escola de Ciências e Tecnologia
da Universidade de Trás-os-Montes e Alto Douro

Nome do Orientador 2

Professor Auxiliar do
Departamento de Engenharias
Escola de Ciências e Tecnologia
da Universidade de Trás-os-Montes e Alto Douro

"In the middle of difficulty lies opportunity"| "No meio da dificuldade encontra-se a oportunidade."

Einstein (1879 – 1955)

"Success is going from failure to failure without losing enthusiasm | Sucesso é ir de fracasso em fracasso sem perder o entusiasmo"

Winston Churchill(1874 – 1965)

-

UNIVERSIDADE DE TRÁS-OS-MONTES E ALTO DOURO
Mestrado em Engenharia Electrotécnica e de Computadores

Os membros do Júri recomendam à Universidade de Trás-os-Montes e Alto Douro a aceitação da dissertação intitulada "**Título da Dissertação-Tese Subtítulo se aplicável**" realizada por **Nome Completo do Aluno** para satisfação parcial dos requisitos do grau de **Doutor**.

agosto 2018

Presidente: **Nome Presidente do Júri**,
Direção do Mestrado em Engenharia Eletrotecnica e de Computadores do Departamento de Engenharias da Universidade de Trás-os-Montes e Alto Douro

Vogais do Júri: **Doutor João Paulo Coelho**,
Professor Adjunto da Escola Superior de Tecnologia e Gestão do Instituto Politécnico de Bragança

Nome do Orientador 1,
Professor Associado com Agregação do Departamento de Engenharias da Escola de Ciências e Tecnologia
da Universidade de Trás-os-Montes e Alto Douro

Nome do Orientador 2,
Professor Auxiliar do Departamento de Engenharias da Escola de Ciências e Tecnologia
da Universidade de Trás-os-Montes e Alto Douro

Título

Autor

Submetido na Universidade de Trás-os-Montes e Alto Douro
para o preenchimento dos requisitos parciais para obtenção do grau de
Mestre/Doutor em Engenharia Electrotécnica e de Computadores

Resumo — Ius wisi imperdiet et, vis ea inimicus dissentias. Has dicit luptatum cu. Accumsan patrioque sea ea. Est ea viderer dissentiet, sit ad tempor oporteat, per causae volumus patrioque id. At pri debet vocent honestatis, postulant disputationi at mei.

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Palavras Chave: Palavra1, Palavra2, Palavra3.

Title

Author Name

Submitted to the University of Trás-os-Montes and Alto Douro
in partial fulfillment of the requirements for the degree of
Master of Science-Philosophiae Doctor in Electrical Engineering and Computers

Abstract — Lorem ipsum dolor sit amet, sed ex nonumes omittam ponderum, sea ut adipiscing inciderint. Vidisse delenit vel ad. Ei nec eripuit deseruisse, ex eos esse maiestatis. Modo vocent lobortis pri id, wisi habemus percipitur ei sit, eu nec cibo quidam dictas. Illum vivendum sed ex.

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Key Words: Word1, Word2, Word3

Agradecimentos

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UTAD, Nome
Vila Real, xx de xxxxx de 20XX

Índice geral

Índice de figuras

Glossário, acrónimos e abreviaturas

Glossário de termos

Lista de acrónimos

Sigla	**Expansão**
CMOS	*Complementary Metal-Oxide-Semiconductor*
DC	*Direct Current* (corrente contínua)
MOSFET	*Metal-Oxide-Semiconductor Field-Effect Transistor*

Introdução

Lorem ipsum dolor sit amet, sed ex nonumes omittam ponderum, sea ut adipiscing inciderint. Vidisse delenit vel ad. Ei nec eripuit deseruisse, ex eos esse maiestatis. Modo vocent lobortis pri id, wisi habemus percipitur ei sit, eu nec cibo quidam dictas. Illum vivendum sed ex 1.1.

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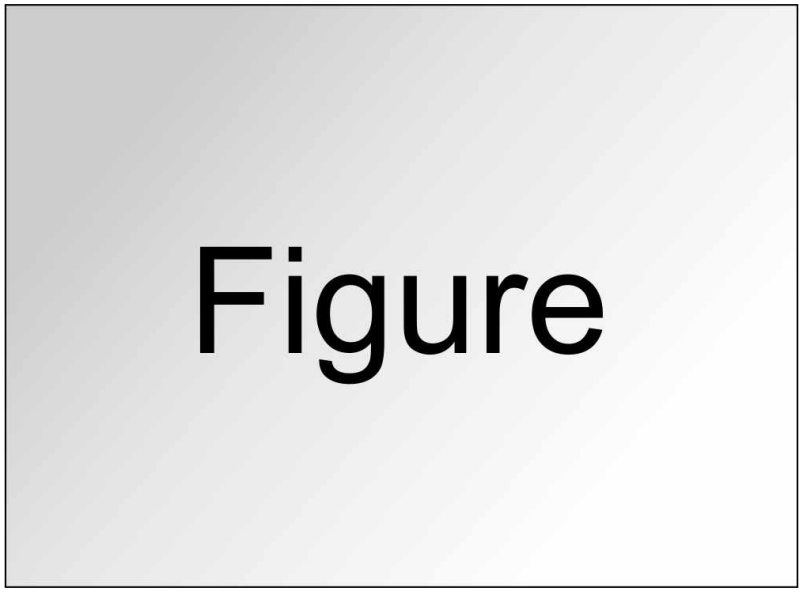

Figura 1.1 – Figure Example

1.1 Motivação e objectivos

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1.2 Organização da dissertação

Viris tempor no eos, has ex causae percipit iracundia, per id platonem inciderint. Ex omnis iusto fastidii mei. Id mea sint tempor. Te idque epicuri pri, at homero regione mel, eam nostrud fabellas facilisis no. At veri molestiae mediocritatem quo, eu accusamus maiestatis scribentur sit, wisi disputando ex pri. An bonorum complectitur sed, ignota petentium ei qui, vidisse salutatus cu per.

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2 Título do Capítulo 1

Exemplo de utilização no sistema de unidades SI 2 min 27 s e de referências no texto (UTAD, 2015) (Japan, 2017).

3 Outro Capítulo

4 Título para figurar no corpo da tese/dissertação

5 Resultados

Exemplo de um algorítmo

1: $LeituraEscuro \leftarrow LeituradaADCantesdoLEDemissorligar$
2: $LeituraLuz \leftarrow LeituradaADCdepoisdoLEDemissorligar$
3: $LeituraReal \leftarrow Leituracorretadovalordossensores$
4: $Limit \leftarrow ValordaADCparaoqualseconsideraproximidadedaparede$
5: **repeat**
6: $LeituraEscuro \leftarrow LerADC$
7: $LEDEmissor \leftarrow ON$
8: $LeituraLuz \leftarrow LerADC$
9: $LEDEmissor \leftarrow OFF$
10: $LeituraReal \leftarrow LeituraLuz - LeituraEscuro$
11: **if** $LeituraReal < Limit$ **then**
12: **return** $Naohaparede$
13: **else**
14: **return** $Haparede$
15: **end if**
16: **until** $TodosSensoresLidos$

6 Conclusão e trabalho futuro

Referências bibliográficas

Japan, N. T. F. (2017). All japan micromouse description. 7

Su, J. H., Lee, C. S., and Chen, C. W. (2016). Sensor fusion algorithms for encoder resolution enhancement in educational mobile robots. In *2016 International Conference on Advanced Robotics and Intelligent Systems (ARIS)*, pages 1–5.

UTAD, V. (2015). MicroMouseRules valente description. 7

Apêndice

Datasheets

A.0.1 DS3231

DS3231

Extremely Accurate I²C-Integrated RTC/TCXO/Crystal

General Description

The DS3231 is a low-cost, extremely accurate I²C real-time clock (RTC) with an integrated temperature-compensated crystal oscillator (TCXO) and crystal. The device incorporates a battery input, and maintains accurate timekeeping when main power to the device is interrupted. The integration of the crystal resonator enhances the long-term accuracy of the device as well as reduces the piece-part count in a manufacturing line. The DS3231 is available in commercial and industrial temperature ranges, and is offered in a 16-pin, 300-mil SO package.

The RTC maintains seconds, minutes, hours, day, date, month, and year information. The date at the end of the month is automatically adjusted for months with fewer than 31 days, including corrections for leap year. The clock operates in either the 24-hour or 12-hour format with an AM/PM indicator. Two programmable time-of-day alarms and a programmable square-wave output are provided. Address and data are transferred serially through an I²C bidirectional bus.

A precision temperature-compensated voltage reference and comparator circuit monitors the status of V_{CC} to detect power failures, to provide a reset output, and to automatically switch to the backup supply when necessary. Additionally, the $\overline{RST}$ pin is monitored as a pushbutton input for generating a µP reset.

Benefits and Features

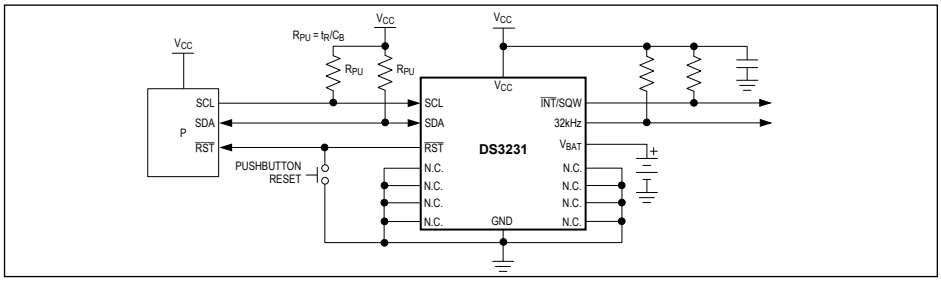
- Highly Accurate RTC Completely Manages All Timekeeping Functions
  - Real-Time Clock Counts Seconds, Minutes, Hours, Date of the Month, Month, Day of the Week, and Year, with Leap-Year Compensation Valid Up to 2100
  - Accuracy ±2ppm from 0°C to +40°C
  - Accuracy ±3.5ppm from -40°C to +85°C
  - Digital Temp Sensor Output: ±3°C Accuracy
  - Register for Aging Trim
  - $\overline{RST}$ Output/Pushbutton Reset Debounce Input
  - Two Time-of-Day Alarms
  - Programmable Square-Wave Output Signal
- Simple Serial Interface Connects to Most Microcontrollers
  - Fast (400kHz) I²C Interface
- Battery-Backup Input for Continuous Timekeeping
  - Low Power Operation Extends Battery-Backup Run Time
  - 3.3V Operation
- Operating Temperature Ranges: Commercial (0°C to +70°C) and Industrial (-40°C to +85°C)
- Underwriters Laboratories® (UL) Recognized

Applications

- Servers
- Telematics
- Utility Power Meters
- GPS

Ordering Information and Pin Configuration appear at end of data sheet.

Typical Operating Circuit



Underwriters Laboratories is a registered certification mark of Underwriters Laboratories Inc.

19-5170; Rev 10; 3/15

maxim integrated™

Absolute Maximum Ratings

Voltage Range on Any Pin Relative to Ground ....-0.3V to +6.0V
Junction-to-Ambient Thermal Resistance (θ_{JA}) (Note 1)73°C/W
Junction-to-Case Thermal Resistance (θ_{JC}) (Note 1) ....23°C/W
Operating Temperature Range
DS3231S .....0°C to +70°C
DS3231SN..... -40°C to +85°C
Junction Temperature.....+125°C
Storage Temperature Range..... -40°C to +85°C
Lead Temperature (soldering, 10s) .....+260°C
Soldering Temperature (reflow, 2 times max) .....+260°C
(see the *Handling*, *PCB Layout*, *and Assembly* section)

Note 1: Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to **www.maximintegrated.com/thermal-tutorial**.

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

Recommended Operating Conditions

(T_A = T_{MIN} to T_{MAX}, unless otherwise noted.) (Notes 2, 3)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
Supply Voltage	V_{CC}		2.3	3.3	5.5	V
	V_{BAT}		2.3	3.0	5.5	V
Logic 1 Input SDA, SCL	V_{IH}		0.7 x V_{CC}		V_{CC} + 0.3	V
Logic 0 Input SDA, SCL	V_{IL}		-0.3		0.3 x V_{CC}	V

Electrical Characteristics

(V_{CC} = 2.3V to 5.5V, V_{CC} = Active Supply (see Table 1), T_A = T_{MIN} to T_{MAX}, unless otherwise noted.) (Typical values are at V_{CC} = 3.3V, V_{BAT} = 3.0V, and T_A = +25°C, unless otherwise noted.) (Notes 2, 3)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Active Supply Current	I_{CCA}	(Notes 4, 5)	V_{CC} = 3.63V			200	µA
			V_{CC} = 5.5V			300	
Standby Supply Current	I_{CCS}	I²C bus inactive, 32kHz output on, SQW output off (Note 5)	V_{CC} = 3.63V			110	µA
			V_{CC} = 5.5V			170	
Temperature Conversion Current	$I_{CCSCONV}$	I²C bus inactive, 32kHz output on, SQW output off	V_{CC} = 3.63V			575	µA
			V_{CC} = 5.5V			650	
Power-Fail Voltage	V_{PF}			2.45	2.575	2.70	V
Logic 0 Output, 32kHz, $\overline{INT}$/SQW, SDA	V_{OL}	I_{OL} = 3mA				0.4	V
Logic 0 Output, $\overline{RST}$	V_{OL}	I_{OL} = 1mA				0.4	V
Output Leakage Current 32kHz, $\overline{INT}$/SQW, SDA	I_{LO}	Output high impedance		-1	0	+1	µA
Input Leakage SCL	I_{LI}			-1		+1	µA
$\overline{RST}$ Pin I/O Leakage	I_{OL}	$\overline{RST}$ high impedance (Note 6)		-200		+10	µA
V_{BAT} Leakage Current (V_{CC} Active)	I_{BATLKG}				25	100	nA

Electrical Characteristics (continued)

(V_{CC} = 2.3V to 5.5V, V_{CC} = Active Supply (see Table 1), T_A = T_{MIN} to T_{MAX}, unless otherwise noted.) (Typical values are at V_{CC} = 3.3V, V_{BAT} = 3.0V, and T_A = +25°C, unless otherwise noted.) (Notes 2, 3)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Output Frequency	f_{OUT}	V_{CC} = 3.3V or V_{BAT} = 3.3V			32.768		kHz
Frequency Stability vs. Temperature (Commercial)	$\Delta f/f_{OUT}$	V_{CC} = 3.3V or V_{BAT} = 3.3V, aging offset = 00h	0°C to +40°C			±2	ppm
			>40°C to +70°C			±3.5	
Frequency Stability vs. Temperature (Industrial)	$\Delta f/f_{OUT}$	V_{CC} = 3.3V or V_{BAT} = 3.3V, aging offset = 00h	-40°C to <0°C			±3.5	ppm
			0°C to +40°C			±2	
			>40°C to +85°C			±3.5	
Frequency Stability vs. Voltage	Δf/V				1		ppm/V
Trim Register Frequency Sensitivity per LSB	Δf/LSB	Specified at:	-40°C		0.7		ppm
			+25°C		0.1		
			+70°C		0.4		
			+85°C		0.8		
Temperature Accuracy	Temp	V_{CC} = 3.3V or V_{BAT} = 3.3V		-3		+3	°C
Crystal Aging	$\Delta f/f_O$	After reflow, not production tested	First year		±1.0		ppm
			0–10 years		±5.0		

Electrical Characteristics

(**V_{CC} = 0V, V_{BAT} = 2.3V to 5.5V**, T_A = T_{MIN} to T_{MAX}, unless otherwise noted.) (Note 2)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
Active Battery Current	I_{BATA}	$\overline{EOSC}$ = 0, BBSQW = 0, SCL = 400kHz (Note 5)	V_{BAT} = 3.63V			70	µA
			V_{BAT} = 5.5V			150	
Timekeeping Battery Current	I_{BATT}	$\overline{EOSC}$ = 0, BBSQW = 0, EN32kHz = 1, SCL = SDA = 0V or SCL = SDA = V_{BAT} (Note 5)	V_{BAT} = 3.63V		0.84	3.0	µA
			V_{BAT} = 5.5V		1.0	3.5	
Temperature Conversion Current	I_{BATTC}	$\overline{EOSC}$ = 0, BBSQW = 0, SCL = SDA = 0V or SCL = SDA = V_{BAT}	V_{BAT} = 3.63V			575	µA
			V_{BAT} = 5.5V			650	
Data-Retention Current	I_{BATTDR}	$\overline{EOSC}$ = 1, SCL = SDA = 0V, +25°C				100	nA

AC Electrical Characteristics

(V_{CC} = $V_{CC(MIN)}$ to $V_{CC(MAX)}$ or V_{BAT} = $V_{BAT(MIN)}$ to $V_{BAT(MAX)}$, V_{BAT} > V_{CC}, T_A = T_{MIN} to T_{MAX}, unless otherwise noted.) (Note 2)

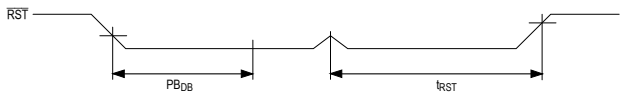
PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
SCL Clock Frequency	f_{SCL}	Fast mode	100		400	kHz
		Standard mode	0		100	
Bus Free Time Between STOP and START Conditions	t_{BUF}	Fast mode	1.3			µs
		Standard mode	4.7			
Hold Time (Repeated) START Condition (Note 7)	$t_{HD:STA}$	Fast mode	0.6			µs
		Standard mode	4.0			
Low Period of SCL Clock	t_{LOW}	Fast mode	1.3			µs
		Standard mode	4.7			
High Period of SCL Clock	t_{HIGH}	Fast mode	0.6			µs
		Standard mode	4.0			
Data Hold Time (Notes 8, 9)	$t_{HD:DAT}$	Fast mode	0		0.9	µs
		Standard mode	0		0.9	
Data Setup Time (Note 10)	$t_{SU:DAT}$	Fast mode	100			ns
		Standard mode	250			
START Setup Time	$t_{SU:STA}$	Fast mode	0.6			µs
		Standard mode	4.7			
Rise Time of Both SDA and SCL Signals (Note 11)	t_R	Fast mode	20 + 0.1C_B		300	ns
		Standard mode			1000	
Fall Time of Both SDA and SCL Signals (Note 11)	t_F	Fast mode	20 + 0.1C_B		300	ns
		Standard mode			300	
Setup Time for STOP Condition	$t_{SU:STO}$	Fast mode	0.6			µs
		Standard mode	4.7			
Capacitive Load for Each Bus Line	C_B	(Note 11)			400	pF
Capacitance for SDA, SCL	$C_{I/O}$			10		pF
Pulse Width of Spikes That Must Be Suppressed by the Input Filter	t_{SP}			30		ns
Pushbutton Debounce	PB_{DB}			250		ms
Reset Active Time	t_{RST}			250		ms
Oscillator Stop Flag (OSF) Delay	t_{OSF}	(Note 12)		100		ms
Temperature Conversion Time	t_{CONV}			125	200	ms

Power-Switch Characteristics

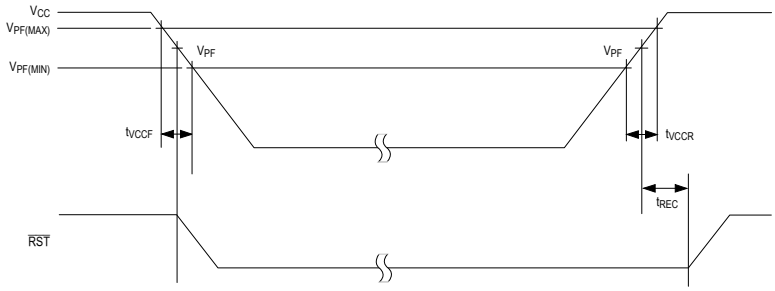
(T_A = T_{MIN} to T_{MAX})

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
V_{CC} Fall Time; $V_{PF(MAX)}$ to $V_{PF(MIN)}$	t_{VCCF}		300			µs
V_{CC} Rise Time; $V_{PF(MIN)}$ to $V_{PF(MAX)}$	t_{VCCR}		0			µs
Recovery at Power-Up	t_{REC}	(Note 13)		250	300	ms

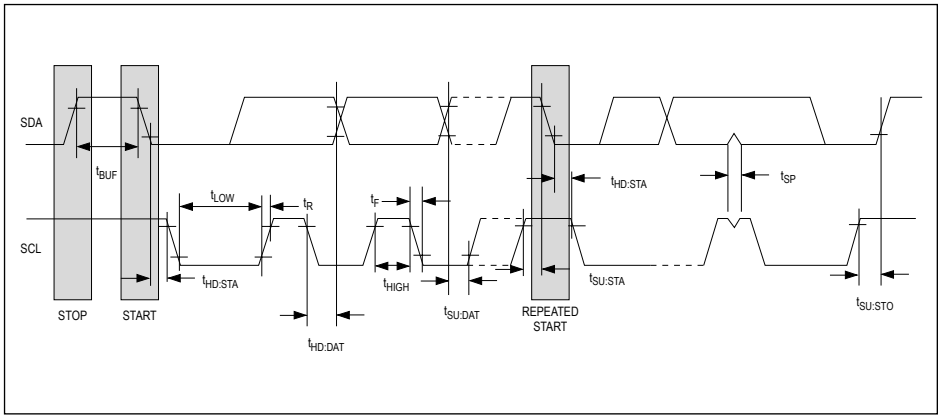
Pushbutton Reset Timing



Power-Switch Timing



Data Transfer on I2C Serial Bus



WARNING: Negative undershoots below -0.3V while the part is in battery-backed mode may cause loss of data.

Note 2: Limits at -40°C are guaranteed by design and not production tested.

Note 3: All voltages are referenced to ground.

Note 4: I_{CCA}—SCL clocking at max frequency = 400kHz.

Note 5: Current is the averaged input current, which includes the temperature conversion current.

Note 6: The $\overline{RST}$ pin has an internal 50kΩ (nominal) pullup resistor to V_{CC}.

Note 7: After this period, the first clock pulse is generated.

Note 8: A device must internally provide a hold time of at least 300ns for the SDA signal (referred to the $V_{IH(MIN)}$ of the SCL signal) to bridge the undefined region of the falling edge of SCL.

Note 9: The maximum $t_{HD:DAT}$ needs only to be met if the device does not stretch the low period (t_{LOW}) of the SCL signal.

Note 10: A fast-mode device can be used in a standard-mode system, but the requirement $t_{SU:DAT} \geq 250ns$ must then be met. This is automatically the case if the device does not stretch the low period of the SCL signal. If such a device does stretch the low period of the SCL signal, it must output the next data bit to the SDA line $t_{R(MAX)} + t_{SU:DAT} = 1000 + 250 = 1250ns$ before the SCL line is released.

Note 11: C_B—total capacitance of one bus line in pF.

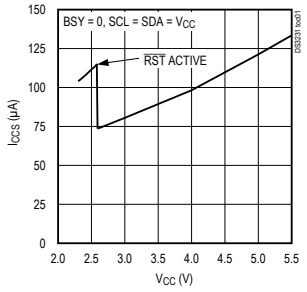
Note 12: The parameter t_{OSF} is the period of time the oscillator must be stopped for the OSF flag to be set over the voltage range of $0.0V \leq V_{CC} \leq V_{CC(MAX)}$ and $2.3V \leq V_{BAT} \leq 3.4V$.

Note 13: This delay applies only if the oscillator is enabled and running. If the $\overline{EOSC}$ bit is a 1, t_{REC} is bypassed and $\overline{RST}$ immediately goes high. The state of $\overline{RST}$ does not affect the I2C interface, RTC, or TCXO.

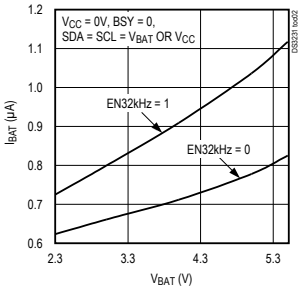
Typical Operating Characteristics

(V_{CC} = +3.3V, T_A = +25°C, unless otherwise noted.)

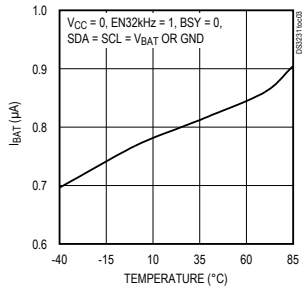
STANDBY SUPPLY CURRENT vs. SUPPLY VOLTAGE



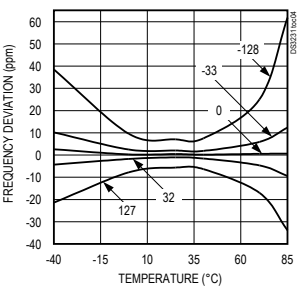
SUPPLY CURRENT vs. SUPPLY VOLTAGE



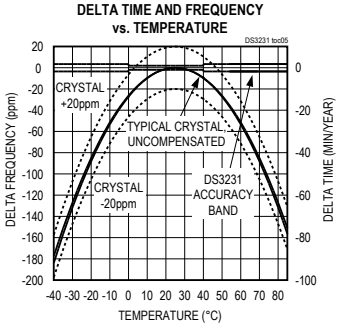
SUPPLY CURRENT vs. TEMPERATURE



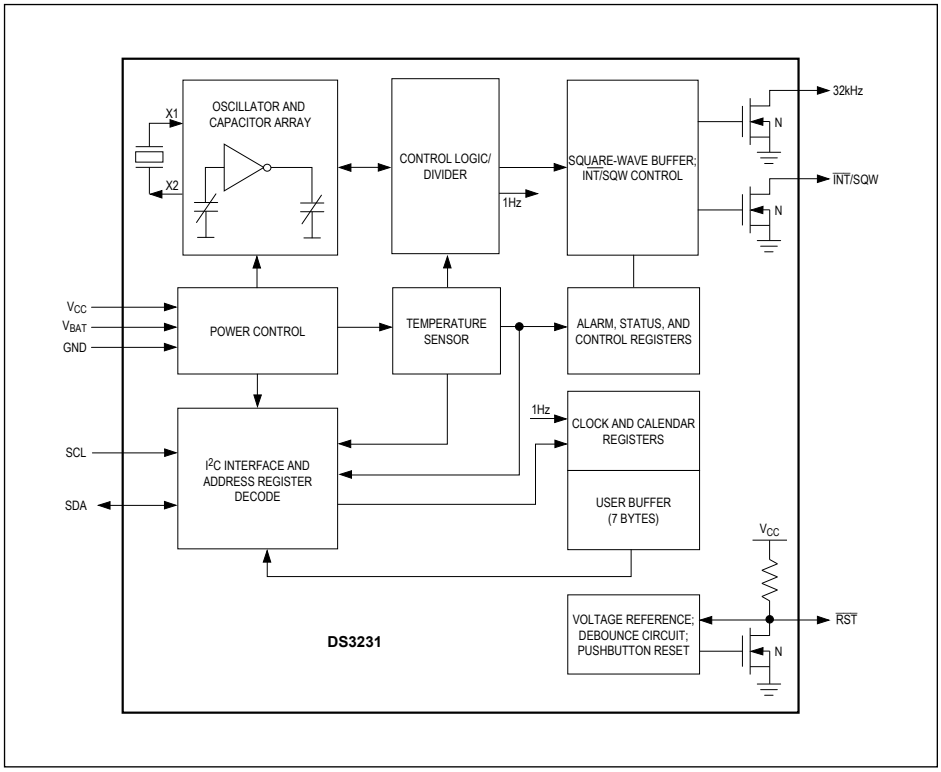
FREQUENCY DEVIATION vs. TEMPERATURE vs. AGING VALUE



DELTA TIME AND FREQUENCY vs. TEMPERATURE



Block Diagram



Pin Description

PIN	NAME	FUNCTION
1	32kHz	32kHz Output. This open-drain pin requires an external pullup resistor. When enabled, the output operates on either power supply. It may be left open if not used.
2	V_{CC}	DC Power Pin for Primary Power Supply. This pin should be decoupled using a 0.1µF to 1.0µF capacitor. If not used, connect to ground.
3	$\overline{INT}$/SQW	Active-Low Interrupt or Square-Wave Output. This open-drain pin requires an external pullup resistor connected to a supply at 5.5V or less. This multifunction pin is determined by the state of the INTCN bit in the Control Register (0Eh). When INTCN is set to logic 0, this pin outputs a square wave and its frequency is determined by RS2 and RS1 bits. When INTCN is set to logic 1, then a match between the timekeeping registers and either of the alarm registers activates the $\overline{INT}$/SQW pin (if the alarm is enabled). Because the INTCN bit is set to logic 1 when power is first applied, the pin defaults to an interrupt output with alarms disabled. The pullup voltage can be up to 5.5V, regardless of the voltage on V_{CC}. If not used, this pin can be left unconnected.
4	$\overline{RST}$	Active-Low Reset. This pin is an open-drain input/output. It indicates the status of V_{CC} relative to the V_{PF} specification. As V_{CC} falls below V_{PF}, the $\overline{RST}$ pin is driven low. When V_{CC} exceeds V_{PF}, for t_{RST}, the $\overline{RST}$ pin is pulled high by the internal pullup resistor. The active-low, open-drain output is combined with a debounced pushbutton input function. This pin can be activated by a pushbutton reset request. It has an internal 50kΩ nominal value pullup resistor to V_{CC}. No external pullup resistors should be connected. If the oscillator is disabled, t_{REC} is bypassed and $\overline{RST}$ immediately goes high.
5–12	N.C.	No Connection. Must be connected to ground.
13	GND	Ground
14	V_{BAT}	Backup Power-Supply Input. When using the device with the V_{BAT} input as the primary power source, this pin should be decoupled using a 0.1µF to 1.0µF low-leakage capacitor. When using the device with the V_{BAT} input as the backup power source, the capacitor is not required. If V_{BAT} is not used, connect to ground. The device is UL recognized to ensure against reverse charging when used with a primary lithium battery. Go to www.maximintegrated.com/qa/info/ul.
15	SDA	Serial Data Input/Output. This pin is the data input/output for the I2C serial interface. This open-drain pin requires an external pullup resistor. The pullup voltage can be up to 5.5V, regardless of the voltage on V_{CC}.
16	SCL	Serial Clock Input. This pin is the clock input for the I2C serial interface and is used to synchronize data movement on the serial interface. Up to 5.5V can be used for this pin, regardless of the voltage on V_{CC}.

Detailed Description

The DS3231 is a serial RTC driven by a temperature-compensated 32kHz crystal oscillator. The TCXO provides a stable and accurate reference clock, and maintains the RTC to within ±2 minutes per year accuracy from -40°C to +85°C. The TCXO frequency output is available at the 32kHz pin. The RTC is a low-power clock/calendar with two programmable time-of-day alarms and a programmable square-wave output. The $\overline{INT}$/SQW provides either an interrupt signal due to alarm conditions or a square-wave output. The clock/calendar provides seconds, minutes, hours, day, date, month, and year information. The date at the end of the month is automatically adjusted for months with fewer than 31 days, including corrections for leap year. The clock operates in either the 24-hour or 12-hour format with an $\overline{AM}$/PM indicator. The internal registers are accessible though an I2C bus interface.

A temperature-compensated voltage reference and comparator circuit monitors the level of V_{CC} to detect power failures and to automatically switch to the backup supply when necessary. The $\overline{RST}$ pin provides an external pushbutton function and acts as an indicator of a power-fail event.

Operation

The block diagram shows the main elements of the DS3231. The eight blocks can be grouped into four functional groups: TCXO, power control, pushbutton function, and RTC. Their operations are described separately in the following sections.

32kHz TCXO

The temperature sensor, oscillator, and control logic form the TCXO. The controller reads the output of the on-chip temperature sensor and uses a lookup table to determine the capacitance required, adds the aging correction in AGE register, and then sets the capacitance selection registers. New values, including changes to the AGE register, are loaded only when a change in the temperature value occurs, or when a user-initiated temperature conversion is completed. Temperature conversion occurs on initial application of V_{CC} and once every 64 seconds afterwards.

Power Control

This function is provided by a temperature-compensated voltage reference and a comparator circuit that monitors the V_{CC} level. When V_{CC} is greater than V_{PF}, the part is powered by V_{CC}. When V_{CC} is less than V_{PF} but greater than V_{BAT}, the DS3231 is powered by V_{CC}. If V_{CC} is less than V_{PF} and is less than V_{BAT}, the device is powered by V_{BAT}. See Table 1.

Table 1. Power Control

SUPPLY CONDITION	ACTIVE SUPPLY
$V_{CC} < V_{PF}$, $V_{CC} < V_{BAT}$	V_{BAT}
$V_{CC} < V_{PF}$, $V_{CC} > V_{BAT}$	V_{CC}
$V_{CC} > V_{PF}$, $V_{CC} < V_{BAT}$	V_{CC}
$V_{CC} > V_{PF}$, $V_{CC} > V_{BAT}$	V_{CC}

To preserve the battery, the first time V_{BAT} is applied to the device, the oscillator will not start up until V_{CC} exceeds V_{PF}, or until a valid I2C address is written to the part. Typical oscillator startup time is less than one second. Approximately 2 seconds after V_{CC} is applied, or a valid I2C address is written, the device makes a temperature measurement and applies the calculated correction to the oscillator. Once the oscillator is running, it continues to run as long as a valid power source is available (V_{CC} or V_{BAT}), and the device continues to measure the temperature and correct the oscillator frequency every 64 seconds.

On the first application of power (V_{CC}) or when a valid I2C address is written to the part (V_{BAT}), the time and date registers are reset to 01/01/00 01 00:00:00 (DD/MM/YY DOW HH:MM:SS).

V_{BAT} Operation

There are several modes of operation that affect the amount of V_{BAT} current that is drawn. While the device is powered by V_{BAT} and the serial interface is active, active battery current, I_{BATA}, is drawn. When the serial interface is inactive, timekeeping current (I_{BATT}), which includes the averaged temperature conversion current, I_{BATTC}, is used (refer to Application Note 3644: *Power Considerations for Accurate Real-Time Clocks* for details). Temperature conversion current, I_{BATTC}, is specified since the system must be able to support the periodic higher current pulse and still maintain a valid voltage level. Data retention current, I_{BATTDR}, is the current drawn by the part when the oscillator is stopped ($\overline{EOSC}$ = 1). This mode can be used to minimize battery requirements for times when maintaining time and date information is not necessary, e.g., while the end system is waiting to be shipped to a customer.

Pushbutton Reset Function

The DS3231 provides for a pushbutton switch to be connected to the $\overline{RST}$ output pin. When the DS3231 is not in a reset cycle, it continuously monitors the $\overline{RST}$ signal for a low going edge. If an edge transition is detected, the DS3231 debounces the switch by pulling the $\overline{RST}$ low. After the internal timer has expired (PB_{DB}), the DS3231 continues to monitor the $\overline{RST}$ line. If the line is still low, the DS3231 continuously monitors the line looking for a rising edge. Upon detecting release, the DS3231 forces the $\overline{RST}$ pin low and holds it low for t_{RST}.

$\overline{RST}$ is also used to indicate a power-fail condition. When V_{CC} is lower than V_{PF}, an internal power-fail signal is generated, which forces the $\overline{RST}$ pin low. When V_{CC} returns to a level above V_{PF}, the $\overline{RST}$ pin is held low for approximately 250ms (t_{REC}) to allow the power supply to stabilize. If the oscillator is not running (see the *Power Control* section) when V_{CC} is applied, t_{REC} is bypassed and $\overline{RST}$ immediately goes high. Assertion of the $\overline{RST}$ output, whether by pushbutton or power-fail detection, does not affect the internal operation of the DS3231.

Real-Time Clock

With the clock source from the TCXO, the RTC provides seconds, minutes, hours, day, date, month, and year information. The date at the end of the month is automatically adjusted for months with fewer than 31 days, including corrections for leap year. The clock operates in either the 24-hour or 12-hour format with an $\overline{AM}$/PM indicator.

The clock provides two programmable time-of-day alarms and a programmable square-wave output. The $\overline{INT}$/SQW pin either generates an interrupt due to alarm condition or outputs a square-wave signal and the selection is controlled by the bit INTCN.

ADDRESS	BIT 7 MSB	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0 LSB	FUNCTION	RANGE
00h	0	10 Seconds			Seconds				Seconds	00–59
01h	0	10 Minutes			Minutes				Minutes	00–59
02h	0	12/$\overline{24}$	$\overline{AM}$/PM 20 Hour	10 Hour	Hour				Hours	1–12 + $\overline{AM}$/PM 00–23
03h	0	0	0	0	0	Day			Day	1–7
04h	0	0	10 Date		Date				Date	01–31
05h	Century	0	0	10 Month	Month				Month/ Century	01–12 + Century
06h	10 Year				Year				Year	00–99
07h	A1M1	10 Seconds			Seconds				Alarm 1 Seconds	00–59
08h	A1M2	10 Minutes			Minutes				Alarm 1 Minutes	00–59
09h	A1M3	12/$\overline{24}$	$\overline{AM}$/PM 20 Hour	10 Hour	Hour				Alarm 1 Hours	1–12 + $\overline{AM}$/PM 00–23
0Ah	A1M4	DY/$\overline{DT}$	10 Date		Day				Alarm 1 Day	1–7
					Date				Alarm 1 Date	1–31
0Bh	A2M2	10 Minutes			Minutes				Alarm 2 Minutes	00–59
0Ch	A2M3	12/$\overline{24}$	$\overline{AM}$/PM 20 Hour	10 Hour	Hour				Alarm 2 Hours	1–12 + $\overline{AM}$/PM 00–23
0Dh	A2M4	DY/$\overline{DT}$	10 Date		Day				Alarm 2 Day	1–7
					Date				Alarm 2 Date	1–31
0Eh	$\overline{EOSC}$	BBSQW	CONV	RS2	RS1	INTCN	A2IE	A1IE	Control	—
0Fh	OSF	0	0	0	EN32kHz	BSY	A2F	A1F	Control/Status	—
10h	SIGN	DATA	DATA	DATA	DATA	DATA	DATA	DATA	Aging Offset	—
11h	SIGN	DATA	DATA	DATA	DATA	DATA	DATA	DATA	MSB of Temp	—
12h	DATA	DATA	0	0	0	0	0	0	LSB of Temp	—

Figure 1. Timekeeping Registers

Note: *Unless otherwise specified, the registers' state is not defined when power is first applied.*

Address Map

Figure 1 shows the address map for the DS3231 timekeeping registers. During a multibyte access, when the address pointer reaches the end of the register space (12h), it wraps around to location 00h. On an I²C START or address pointer incrementing to location 00h, the current time is transferred to a second set of registers. The time information is read from these secondary registers, while the clock may continue to run. This eliminates the need to reread the registers in case the main registers update during a read.

I²C Interface

The I²C interface is accessible whenever either V_{CC} or V_{BAT} is at a valid level. If a microcontroller connected to the DS3231 resets because of a loss of V_{CC} or other event, it is possible that the microcontroller and DS3231 I²C communications could become unsynchronized, e.g., the microcontroller resets while reading data from the DS3231. When the microcontroller resets, the DS3231 I²C interface may be placed into a known state by toggling SCL until SDA is observed to be at a high level. At that point the microcontroller should pull SDA low while SCL is high, generating a START condition.

Clock and Calendar

The time and calendar information is obtained by reading the appropriate register bytes. Figure 1 illustrates the RTC registers. The time and calendar data are set or initialized by writing the appropriate register bytes. The contents of the time and calendar registers are in the binary-coded

decimal (BCD) format. The DS3231 can be run in either 12-hour or 24-hour mode. Bit 6 of the hours register is defined as the 12- or 24-hour mode select bit. When high, the 12-hour mode is selected. In the 12-hour mode, bit 5 is the AM/PM bit with logic-high being PM. In the 24-hour mode, bit 5 is the 20-hour bit (20–23 hours). The century bit (bit 7 of the month register) is toggled when the years register overflows from 99 to 00.

The day-of-week register increments at midnight. Values that correspond to the day of week are user-defined but must be sequential (i.e., if 1 equals Sunday, then 2 equals Monday, and so on). Illogical time and date entries result in undefined operation.

When reading or writing the time and date registers, secondary (user) buffers are used to prevent errors when the internal registers update. When reading the time and date registers, the user buffers are synchronized to the internal registers on any START and when the register pointer rolls over to zero. The time information is read from these secondary registers, while the clock continues to run. This eliminates the need to reread the registers in case the main registers update during a read.

The countdown chain is reset whenever the seconds register is written. Write transfers occur on the acknowledge from the DS3231. Once the countdown chain is reset, to avoid rollover issues the remaining time and date registers must be written within 1 second. The 1Hz square-wave output, if enabled, transitions high 500ms after the seconds data transfer, provided the oscillator is already running.

Alarms

The DS3231 contains two time-of-day/date alarms. Alarm 1 can be set by writing to registers 07h to 0Ah. Alarm 2 can be set by writing to registers 0Bh to 0Dh. The alarms can be programmed (by the alarm enable and INTCN bits of the control register) to activate the INT/SQW output on an alarm match condition. Bit 7 of each of the time-of-day/date alarm registers are mask bits (Table 2). When all the mask bits for each alarm are logic 0, an alarm only occurs when the values in the timekeeping registers match the corresponding values stored in the time-of-day/date alarm registers. The alarms can also be programmed to repeat every second, minute, hour, day, or date. Table 2 shows the possible settings. Configurations not listed in the table will result in illogical operation.

The DY/DT bits (bit 6 of the alarm day/date registers) control whether the alarm value stored in bits 0 to 5 of that register reflects the day of the week or the date of the month. If DY/DT is written to logic 0, the alarm will be the result of a match with date of the month. If DY/DT is written to logic 1, the alarm will be the result of a match with day of the week.

When the RTC register values match alarm register settings, the corresponding Alarm Flag ‘A1F’ or ‘A2F’ bit is set to logic 1. If the corresponding Alarm Interrupt Enable ‘A1IE’ or ‘A2IE’ is also set to logic 1 and the INTCN bit is set to logic 1, the alarm condition will activate the INT/SQW signal. The match is tested on the once-per-second update of the time and date registers.

Table 2. Alarm Mask Bits

DY/DT	ALARM 1 REGISTER MASK BITS (BIT 7)				ALARM RATE
	A1M4	A1M3	A1M2	A1M1	
X	1	1	1	1	Alarm once per second
X	1	1	1	0	Alarm when seconds match
X	1	1	0	0	Alarm when minutes and seconds match
X	1	0	0	0	Alarm when hours, minutes, and seconds match
0	0	0	0	0	Alarm when date, hours, minutes, and seconds match
1	0	0	0	0	Alarm when day, hours, minutes, and seconds match

DY/DT	ALARM 2 REGISTER MASK BITS (BIT 7)			ALARM RATE
	A2M4	A2M3	A2M2	
X	1	1	1	Alarm once per minute (00 seconds of every minute)
X	1	1	0	Alarm when minutes match
X	1	0	0	Alarm when hours and minutes match
0	0	0	0	Alarm when date, hours, and minutes match
1	0	0	0	Alarm when day, hours, and minutes match

Control Register (0Eh)

	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
NAME:	$\overline{EOSC}$	BBSQW	CONV	RS2	RS1	INTCN	A2IE	A1IE
POR:	0	0	0	1	1	1	0	0

Special-Purpose Registers

The DS3231 has two additional registers (control and status) that control the real-time clock, alarms, and square-wave output.

Control Register (0Eh)

Bit 7: Enable Oscillator ($\overline{EOSC}$). When set to logic 0, the oscillator is started. When set to logic 1, the oscillator is stopped when the DS3231 switches to V_{BAT}. This bit is clear (logic 0) when power is first applied. When the DS3231 is powered by V_{CC}, the oscillator is always on regardless of the status of the $\overline{EOSC}$ bit. When $\overline{EOSC}$ is disabled, all register data is static.

Bit 6: Battery-Backed Square-Wave Enable (BBSQW). When set to logic 1 with INTCN = 0 and $V_{CC} < V_{PF}$, this bit enables the square wave. When BBSQW is logic 0, the $\overline{INT}$/SQW pin goes high impedance when $V_{CC} < V_{PF}$. This bit is disabled (logic 0) when power is first applied.

Bit 5: Convert Temperature (CONV). Setting this bit to 1 forces the temperature sensor to convert the temperature into digital code and execute the TCXO algorithm to update the capacitance array to the oscillator. This can only happen when a conversion is not already in progress. The user should check the status bit BSY before forcing the controller to start a new TCXO execution. A user-initiated temperature conversion does not affect the internal 64-second update cycle.

A user-initiated temperature conversion does not affect the BSY bit for approximately 2ms. The CONV bit remains at a 1 from the time it is written until the conversion is finished, at which time both CONV and BSY go to 0. The CONV bit should be used when monitoring the status of a user-initiated conversion.

Bits 4 and 3: Rate Select (RS2 and RS1). These bits control the frequency of the square-wave output when the square wave has been enabled. The following table shows the square-wave frequencies that can be selected with the RS bits. These bits are both set to logic 1 (8.192kHz) when power is first applied.

SQUARE-WAVE OUTPUT FREQUENCY

RS2	RS1	SQUARE-WAVE OUTPUT FREQUENCY
0	0	1Hz
0	1	1.024kHz
1	0	4.096kHz
1	1	8.192kHz

Bit 2: Interrupt Control (INTCN). This bit controls the $\overline{INT}$/SQW signal. When the INTCN bit is set to logic 0, a square wave is output on the $\overline{INT}$/SQW pin. When the INTCN bit is set to logic 1, then a match between the timekeeping registers and either of the alarm registers activates the $\overline{INT}$/SQW output (if the alarm is also enabled). The corresponding alarm flag is always set regardless of the state of the INTCN bit. The INTCN bit is set to logic 1 when power is first applied.

Bit 1: Alarm 2 Interrupt Enable (A2IE). When set to logic 1, this bit permits the alarm 2 flag (A2F) bit in the status register to assert $\overline{INT}$/SQW (when INTCN = 1). When the A2IE bit is set to logic 0 or INTCN is set to logic 0, the A2F bit does not initiate an interrupt signal. The A2IE bit is disabled (logic 0) when power is first applied.

Bit 0: Alarm 1 Interrupt Enable (A1IE). When set to logic 1, this bit permits the alarm 1 flag (A1F) bit in the status register to assert $\overline{INT}$/SQW (when INTCN = 1). When the A1IE bit is set to logic 0 or INTCN is set to logic 0, the A1F bit does not initiate the $\overline{INT}$/SQW signal. The A1IE bit is disabled (logic 0) when power is first applied.

Status Register (0Fh)

	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
NAME:	OSF	0	0	0	EN32kHz	BSY	A2F	A1F
POR:	1	0	0	0	1	X	X	X

Status Register (0Fh)

Bit 7: Oscillator Stop Flag (OSF). A logic 1 in this bit indicates that the oscillator either is stopped or was stopped for some period and may be used to judge the validity of the timekeeping data. This bit is set to logic 1 any time that the oscillator stops. The following are examples of conditions that can cause the OSF bit to be set:

1) The first time power is applied.
2) The voltages present on both V_{CC} and V_{BAT} are insufficient to support oscillation.
3) The $\overline{EOSC}$ bit is turned off in battery-backed mode.
4) External influences on the crystal (i.e., noise, leakage, etc.).

This bit remains at logic 1 until written to logic 0.

Bit 3: Enable 32kHz Output (EN32kHz). This bit controls the status of the 32kHz pin. When set to logic 1, the 32kHz pin is enabled and outputs a 32.768kHz square-wave signal. When set to logic 0, the 32kHz pin goes to a high-impedance state. The initial power-up state of this bit is logic 1, and a 32.768kHz square-wave signal appears at the 32kHz pin after a power source is applied to the DS3231 (if the oscillator is running).

Bit 2: Busy (BSY). This bit indicates the device is busy executing TCXO functions. It goes to logic 1 when the conversion signal to the temperature sensor is asserted and then is cleared when the device is in the 1-minute idle state.

Bit 1: Alarm 2 Flag (A2F). A logic 1 in the alarm 2 flag bit indicates that the time matched the alarm 2 registers. If the A2IE bit is logic 1 and the INTCN bit is set to logic 1, the $\overline{INT}$/SQW pin is also asserted. A2F is cleared when written to logic 0. This bit can only be written to logic 0. Attempting to write to logic 1 leaves the value unchanged.

Bit 0: Alarm 1 Flag (A1F). A logic 1 in the alarm 1 flag bit indicates that the time matched the alarm 1 registers. If the A1IE bit is logic 1 and the INTCN bit is set to logic 1, the $\overline{INT}$/SQW pin is also asserted. A1F is cleared when written to logic 0. This bit can only be written to logic 0. Attempting to write to logic 1 leaves the value unchanged.

Aging Offset

The aging offset register takes a user-provided value to add to or subtract from the codes in the capacitance array registers. The code is encoded in two's complement, with bit 7 representing the sign bit. One LSB represents one small capacitor to be switched in or out of the capacitance array at the crystal pins. The aging offset register capacitance value is added or subtracted from the capacitance value that the device calculates for each temperature compensation. The offset register is added to the capacitance array during a normal temperature conversion, if the temperature changes from the previous conversion, or during a manual user conversion (setting the CONV bit). To see the effects of the aging register on the 32kHz output frequency immediately, a manual conversion should be started after each aging register change.

Positive aging values add capacitance to the array, slowing the oscillator frequency. Negative values remove capacitance from the array, increasing the oscillator frequency.

The change in ppm per LSB is different at different temperatures. The frequency vs. temperature curve is shifted by the values used in this register. At +25°C, one LSB typically provides about 0.1ppm change in frequency.

Use of the aging register is not needed to achieve the accuracy as defined in the EC tables, but could be used to help compensate for aging at a given temperature. See the *Typical Operating Characteristics* section for a graph showing the effect of the register on accuracy over temperature.

Aging Offset (10h)

	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
NAME:	Sign	Data	Data	Data	Data	Data	Data	Data
POR:	0	0	0	0	0	0	0	0

Temperature Register (Upper Byte) (11h)

	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
NAME:	Sign	Data	Data	Data	Data	Data	Data	Data
POR:	0	0	0	0	0	0	0	0

Temperature Register (Lower Byte) (12h)

	BIT 7	BIT 6	BIT 5	BIT 4	BIT 3	BIT 2	BIT 1	BIT 0
NAME:	Data	Data	0	0	0	0	0	0
POR:	0	0	0	0	0	0	0	0

Temperature Registers (11h–12h)

Temperature is represented as a 10-bit code with a resolution of 0.25°C and is accessible at location 11h and 12h. The temperature is encoded in two's complement format. The upper 8 bits, the integer portion, are at location 11h and the lower 2 bits, the fractional portion, are in the upper nibble at location 12h. For example, 00011001 01b = +25.25°C. Upon power reset, the registers are set to a default temperature of 0°C and the controller starts a temperature conversion. The temperature is read on initial application of V_{CC} or I2C access on V_{BAT} and once every 64 seconds afterwards. The temperature registers are updated after each user-initiated conversion and on every 64-second conversion. The temperature registers are read-only.

I2C Serial Data Bus

The DS3231 supports a bidirectional I2C bus and data transmission protocol. A device that sends data onto the bus is defined as a transmitter and a device receiving data is defined as a receiver. The device that controls the message is called a master. The devices that are controlled by the master are slaves. The bus must be controlled by a master device that generates the serial clock (SCL), controls the bus access, and generates the START and STOP conditions. The DS3231 operates as a slave on the I2C bus. Connections to the bus are made through the SCL input and open-drain SDA I/O lines. Within the bus specifications, a standard mode (100kHz maximum clock rate) and a fast mode (400kHz maximum clock rate) are defined. The DS3231 works in both modes.

The following bus protocol has been defined (Figure 2):

- Data transfer may be initiated only when the bus is not busy.
- During data transfer, the data line must remain stable whenever the clock line is high. Changes in the data line while the clock line is high are interpreted as control signals.

Accordingly, the following bus conditions have been defined:

Bus not busy: Both data and clock lines remain high.

START data transfer: A change in the state of the data line from high to low, while the clock line is high, defines a START condition.

STOP data transfer: A change in the state of the data line from low to high, while the clock line is high, defines a STOP condition.

Data valid: The state of the data line represents valid data when, after a START condition, the data line is stable for the duration of the high period of the clock signal. The data on the line must be changed during the low period of the clock signal. There is one clock pulse per bit of data.

Each data transfer is initiated with a START condition and terminated with a STOP condition. The number of data bytes transferred between the START and the STOP conditions is not limited, and is determined by the master device. The information is transferred bytewise and each receiver acknowledges with a ninth bit.

Acknowledge: Each receiving device, when addressed, is obliged to generate an acknowledge after the reception of each byte. The master device must generate an extra clock pulse, which is associated with this acknowledge bit.

A device that acknowledges must pull down the SDA line during the acknowledge clock pulse in such a way that the SDA line is stable low during the high period of the acknowledge-related clock pulse. Of course, setup and hold times must be taken into account. A master must signal an end of data to the slave by not generat-

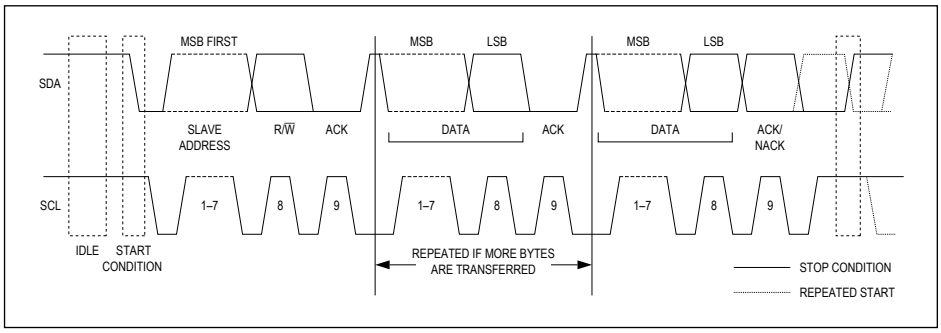


Figure 2. I2C Data Transfer Overview

ing an acknowledge bit on the last byte that has been clocked out of the slave. In this case, the slave must leave the data line high to enable the master to generate the STOP condition.

Figures 3 and 4 detail how data transfer is accomplished on the I2C bus. Depending upon the state of the R/$\overline{W}$ bit, two types of data transfer are possible:

Data transfer from a master transmitter to a slave receiver. The first byte transmitted by the master is the slave address. Next follows a number of data bytes. The slave returns an acknowledge bit after each received byte. Data is transferred with the most significant bit (MSB) first.

Data transfer from a slave transmitter to a master receiver. The first byte (the slave address) is transmitted by the master. The slave then returns an acknowledge bit. Next follows a number of data bytes transmitted by the slave to the master. The master returns an acknowledge bit after all received bytes other than the

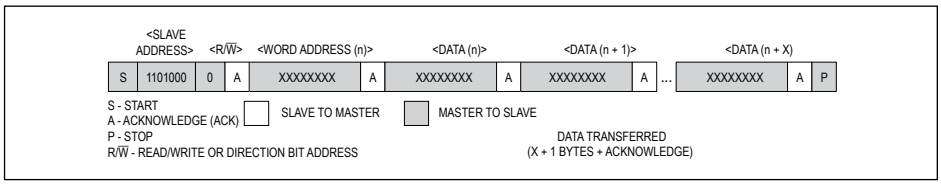


Figure 3. Data Write—Slave Receiver Mode

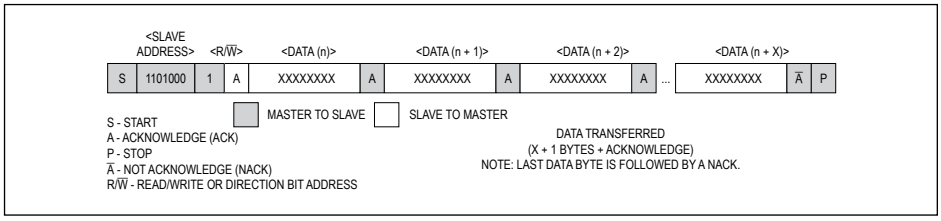


Figure 4. Data Read—Slave Transmitter Mode

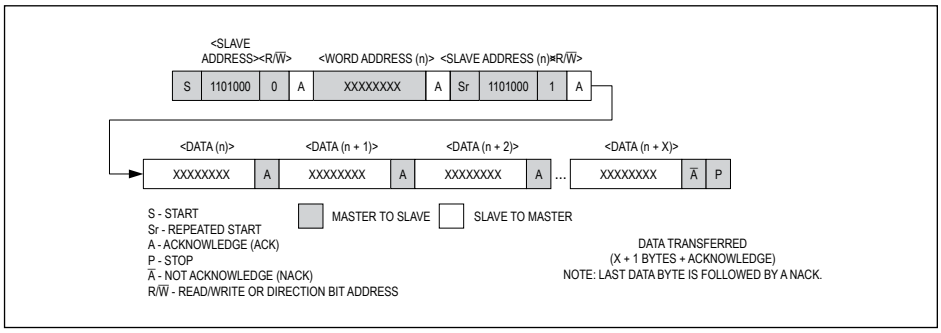


Figure 5. Data Write/Read (Write Pointer, Then Read)—Slave Receive and Transmit

last byte. At the end of the last received byte, a not acknowledge is returned.

The master device generates all the serial clock pulses and the START and STOP conditions. A transfer is ended with a STOP condition or with a repeated START condition. Since a repeated START condition is also the beginning of the next serial transfer, the bus will not be released. Data is transferred with the most significant bit (MSB) first.

The DS3231 can operate in the following two modes:

Slave receiver mode (DS3231 write mode): Serial data and clock are received through SDA and SCL. After each byte is received, an acknowledge bit is transmitted. START and STOP conditions are recognized as the beginning and end of a serial transfer. Address recognition is performed by hardware after reception of the slave address and direction bit. The slave address byte is the first byte received after the master generates the START condition. The slave address byte contains the 7-bit DS3231 address, which is 1101000, followed by the direction bit (R/$\overline{W}$), which is 0 for a write. After receiving and decoding the slave address byte, the DS3231 outputs an acknowledge on SDA. After the DS3231 acknowledges the slave address + write bit, the master transmits a word address to the DS3231. This sets the register pointer on the DS3231, with the DS3231 acknowledging the transfer. The master may then transmit zero or more bytes of data, with the DS3231 acknowledging each byte received. The register pointer increments after each data byte is transferred. The master generates a STOP condition to terminate the data write.

Slave transmitter mode (DS3231 read mode): The first byte is received and handled as in the slave receiver mode. However, in this mode, the direction bit indicates that the transfer direction is reversed. Serial data is transmitted on SDA by the DS3231 while the serial clock is input on SCL. START and STOP conditions are recognized as the beginning and end of a serial transfer. Address recognition is performed by hardware after reception of the slave address and direction bit. The slave address byte is the first byte received after the master generates a START condition. The slave address byte contains the 7-bit DS3231 address, which is 1101000, followed by the direction bit (R/$\overline{W}$), which is 1 for a read. After receiving and decoding the slave address byte, the DS3231 outputs an acknowledge on SDA. The DS3231 then begins to transmit data starting with the register address pointed to by the register pointer. If the register pointer is not written to before the initiation of a read mode, the first address that is read is the last one stored in the register pointer. The DS3231 must receive a not acknowledge to end a read.

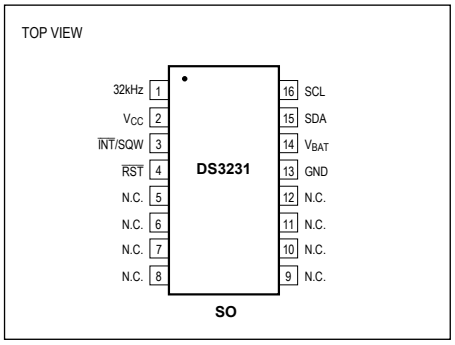
Handling, PCB Layout, and Assembly

The DS3231 package contains a quartz tuning-fork crystal. Pick-and-place equipment can be used, but precautions should be taken to ensure that excessive shocks are avoided. Ultrasonic cleaning should be avoided to prevent damage to the crystal.

Avoid running signal traces under the package, unless a ground plane is placed between the package and the signal line. All N.C. (no connect) pins must be connected to ground.

Moisture-sensitive packages are shipped from the factory dry packed. Handling instructions listed on the package label must be followed to prevent damage during reflow. Refer to the IPC/JEDEC J-STD-020 standard for moisture-sensitive device (MSD) classifications and reflow profiles. Exposure to reflow is limited to 2 times maximum.

Pin Configuration



Chip Information

SUBSTRATE CONNECTED TO GROUND

PROCESS: CMOS

Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
DS3231S#	0°C to +70°C	16 SO
DS3231SN#	-40°C to +85°C	16 SO

#Denotes an RoHS-compliant device that may include lead (Pb) that is exempt under RoHS requirements. The lead finish is JESD97 category e3, and is compatible with both lead-based and lead-free soldering processes. A "#" anywhere on the top mark denotes an RoHS-compliant device.

Package Information

For the latest package outline information and land patterns (footprints), go to **www.maximintegrated.com/packages**. Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	OUTLINE NO.	LAND PATTERN NO.
16 SO	W16#H2	21-0042	90-0107

Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	1/05	Initial release.	—
1	2/05	Changed Digital Temp Sensor Output from ±2°C to ±3°C.	1, 3
		Updated *Typical Operating Circuit*.	1
		Changed T_A = -40°C to +85°C to T_A = T_{MIN} to T_{MAX}.	2, 3, 4
		Updated *Block Diagram*.	8
2	6/05	Added “UL Recognized” to Features; added lead-free packages and removed S from top mark info in *Ordering Information* table; added ground connections to the N.C. pin in the Typical Operating Circuit.	1
		Added “noncondensing” to operating temperature range; changed V_{PF} MIN from 2.35V to 2.45V.	2
		Added aging offset specification.	3
		Relabeled TOC4.	7
		Added arrow showing input on X1 in the *Block Diagram*.	8
		Updated pin descriptions for V_{CC} and V_{BAT}.	9
		Added the I2C Interface section.	10
		Figure 1: Added sign bit to aging and temperature registers; added MSB and LSB.	11
		Corrected title for rate select bits frequency table.	13
		Added note that frequency stability over temperature spec is with aging offset register = 00h; changed bit 7 from Data to Sign (Crystal Aging Offset Register).	14
		Changed bit 7 from Data to Sign (Temperature Register); correct pin definitions in *I2C Serial Data Bus* section.	15
		Modified the *Handing*, *PC Board Layout*, and *Assembly* section to refer to J-STD-020 for reflow profiles for lead-free and leaded packages.	17
3	11/05	Changed lead-free packages to RoHS-compliant packages.	1
4	10/06	Changed $\overline{RST}$ and UL bullets in *Features*.	1
		Changed EC condition “V_{CC} > V_{BAT}” to “V_{CC} = Active Supply (see Table 1).”	2, 3
		Modified Note 12 to correct t_{REC} operation.	6
		Added various conditions text to TOCs 1, 2, and 3.	7
		Added text to pin descriptions for 32kHz, V_{CC}, and $\overline{RST}$.	9
		Table 1: Changed column heading “Powered By” to “Active Supply”; changed “applied” to “exceeds V_{PF}” in the *Power Control* section.	10
		Indicated BBSQW applies to both SQW and interrupts; simplified temp convert description (bit 5); added “output” to $\overline{INT}$/SQW (bit 2).	13
		Changed the *Crystal Aging* section to the *Aging Offset* section; changed “this bit indicates” to “this bit controls” for the enable 32kHz output bit.	14
5	4/08	Added Warning note to EC table notes; updated Note 12.	6
		Updated the *Typical Operating Characteristics* graphs.	7
		In the *Power Control* section, added information about the POR state of the time and date registers; in the *Real-Time Clock* section, added to the description of the RST function.	10
		In Figure 1, corrected the months date range for 04h from 00–31 to 01–31.	11

Revision History (continued)

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
6	10/08	Updated the *Typical Operating Circuit*.	1
		Removed the V_{PU} parameter from the *Recommended DC Operating Conditions* table and added verbiage about the pullup to the *Pin Description* table for $\overline{INT}$/SQW, SDA, and SCL.	2, 9
		Added the Delta Time and Frequency vs. Temperature graph in the *Typical Operating Characteristics* section.	7
		Updated the *Block Diagram*.	8
		Added the V_{BAT} *Operation* section, improved some sections of text for the *32kHz TCXO* and *Pushbutton Reset Function* sections.	10
		Added the register bit POR values to the register tables.	13, 14, 15
		Updated the *Aging Offset* and *Temperature Registers (11h–12h)* sections.	14, 15
		Updated the I2C timing diagrams (Figures 3, 4, and 5).	16, 17
7	3/10	Removed the “S” from the top mark in the *Ordering Information* table and the *Pin Configuration* to match the packaging engineering marking specification.	1, 18
8	7/10	Updated the *Typical Operating Circuit*; removed the “Top Mark” column from the *Ordering Information*; in the *Absolute Maximum Ratings* section, added the theta-JA and theta-JC thermal resistances and Note 1, and changed the soldering temperature to +260°C (lead(Pb)-free) and +240°C (leaded); updated the functional description of the V_{BAT} pin in the *Pin Description*; changed the timekeeping registers 02h, 09h, and 0Ch to “20 Hour” in Bit 5 of Figure 1; updated the BBSQW bit description in the *Control Register (0Eh)* section; added the land pattern no. to the *Package Information* table.	1, 2, 3, 4, 6, 9, 11, 12, 13, 18
9	1/13	Updated *Absolute Maximum Ratings*, and last paragraph in *Power Control* section	2, 10
10	3/15	Revised *Benefits and Features* section.	1

